Timer Control for Triac and Relay

Description

The timer control circuit, U2100B, uses bipolar technology. It has different mode selections (Zero voltage switch, Phase control, Relay control). The output stage is

Features

- Adjustable and retriggerable tracking time
- Window monitoring for sensor input
- Enable input for triggering
- Internal noise suppression (40 ms) and retrigger blocking (640 ms)
- Two or three wire application



triggered according to input conditions. It can be used in triac application for two or three wire system as a power switch.

Applications

- Motion detectors
- Touch sensors
- Timer

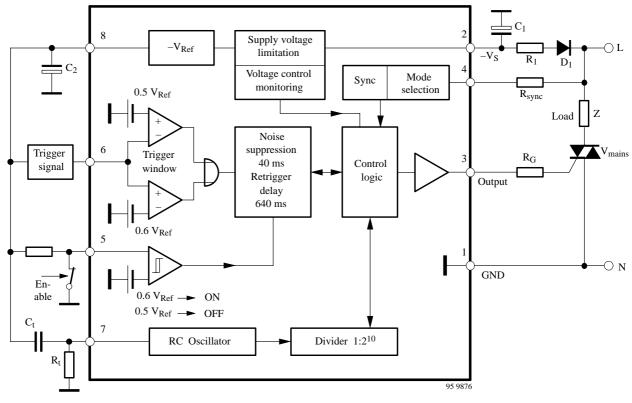
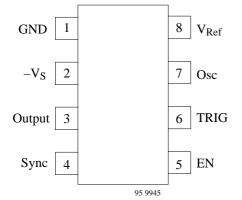


Figure 1. Block diagram with external circuit

U2100B

Pin Description



Pin	Symbol	Function
1	GND	Reference point
2	$-V_S$	Supply voltage
3	Output	Driver output
4	Sync	Synchronisation and mode selection
5	EN	Enable
6	TRIG	Input trigger signal
7	Osc	RC Oscillator
8	V _{Ref}	Reference voltage

General Description

Monostable integrated power control circuit, U2100B, can be used according to mode selection in relay's or triac's applications. Beyond that, it can be used in triac-application for two wire system as power switch, (being the load in series to the switch) whereas the supply voltage for the control unit is gained from phase rest angle (α_{min} -operation).

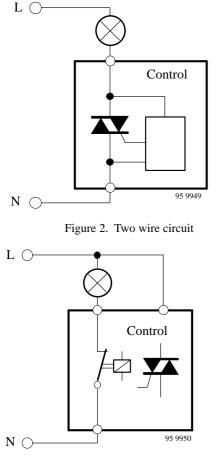


Figure 3. Three wire circuit

For three wire switch, two modes of operations are possible:

- Zero voltage switch operation for triac control
- Static operation for relay control

Mode Selection Pin 4 and Supply Voltage Pin 2

Operation modes can be selected by external voltage at the sync. input Pin 4 (clamping). Mode selection determines the current requirement of driver stage for relay's or triac's and hence the selection of supply voltage.

Zero Voltage Switch Operation, Figure 4

Selection condition:

 V_4 = internal sync limitation, without external clamping

$$\mathbf{R}_{1} \approx 0.85 \frac{\mathbf{V}_{\mathrm{M}} - \mathbf{V}_{\mathrm{S}}}{2 \ \mathbf{I}_{\mathrm{tot}}}$$

$$\mathbf{I}_{tot} = \mathbf{I}_{\mathbf{S}} + \mathbf{I}_{\mathbf{p}} + \mathbf{I}_{\mathbf{X}}$$

whereas:

- I_S = Supply current of IC without load
- I_P = Average trigger current I_G
- I_X = External circuit current requirement
- V_M = Mains voltage

Required firing pulse width tp

$$t_{p} = \frac{2}{\omega} \arcsin\left(\frac{I_{L} \times V_{M}}{P \times \sqrt{2}}\right)$$

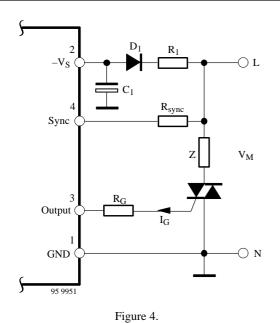
whereas:

 I_L = Triac latching current

 \vec{P} = Power at load Z

$$R_{sync}[k\Omega] \approx \frac{V_{M}[V] \times \sqrt{2} \sin \left(\omega \times t_{p}[s]\right) - 0.7}{1.8 \times 10^{-2}} - 176$$





α_{min} -Operation, Figure 6

Selection condition:

 $-V_4 = 6.5$ to 7.8 V $+V_4 = int.$ limitation

$$R_{\alpha max} = R_{sync} \frac{3.6 \text{ V}}{\text{V}_{\text{R(peak)}} - 3.6 \text{ V}}$$

$$R_{\alpha min} = R_{sync} \frac{10 \text{ V}}{\text{V}_{M} \times \sqrt{2} - 10 \text{ V}}$$

 $V_{R(peak)}$ is the peak voltage of the rest phase angle, which should be high enough to generate the supply voltage, V_S .

DC Operation, Figure 5

Selection condition:

 $R_0 \approx 1/10 X_c$

 $+V_4 = 6.1 V -V_4 = int.$ limitation whereas:

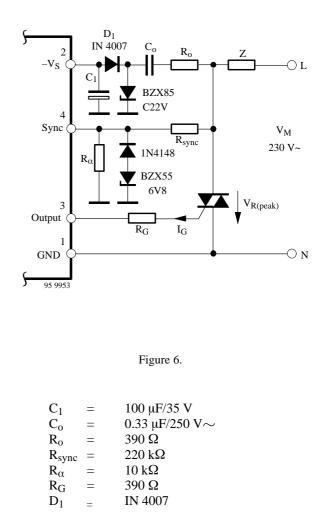
$$X_{c} = 0.85 \frac{V_{M} - V_{S}}{I_{tot}}$$

$$I_{tot} = I_{S} + I_{Rel} + I_{X}$$

$$C_{0} = \frac{1}{\omega \times X_{C}}$$

$$Rel \qquad V_{M} \qquad$$

Figure 5.



Tracking Time Pin 7

An internal RC oscillator with following divider stage $1:2^{10}$ allows a very long and reproducible tracking time.

RC-values for required final time, t_t , can be calculated as follows:

$$R_{t}[\Omega] = \frac{t_{t}[s] \ 10^{6}}{1.6 \ 1024 \ C_{t}[\mu F]}$$

$$C_{t}[\mu F] = \frac{t_{t}[s] \ 10^{6}}{1.6 \ 1024 \ R_{t}[\Omega]}$$

$$t_{t}[s] = \frac{C_{t}[\mu F] \times R_{t}[\Omega] \times 1.6 \times 1024}{10^{6}}$$

Trigger Inputs Pins 5 and 6, Figures 7 and 8

Two AND-connected, identical inputs determine the trigger conditions of monostable time stages, i.e., both inputs must be in position "ON" so that the output is switched ON. The tracking time starts after the trigger conditions has elapsed. The output ON state is given until the tracking time is over.

Input Pin 5 is a simple comparator whereas input Pin 6 is built up as a window discriminator.

Noise suppression for $t_{ON} = 40$ ms guarantee, that there is no peak noise signals at the inputs which could trigger the circuit.

At the same time, the retrigger is delayed for a duration of 640 ms (t_{OFF}), to avoid noise signal to trigger the relay.

Absolute Maximum Ratings

Reference point Pin 1, unless otherwise specified

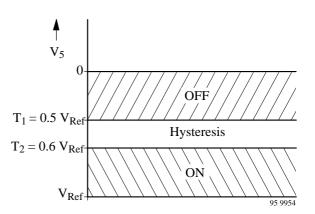


Figure 7. Trigger condition, Pin 5

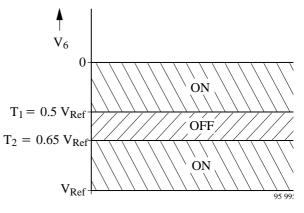


Figure 8. Trigger condition, Pin 6

Parameters		Symbol	Value	Unit	
Supply	Pin 2				
Supply current		-I _S	10	mA	
Peak current $t \le 10 \ \mu s$		$-i_s$	60	mA	
Supply voltage		$-V_S$	32	V	
Reference voltage source	Pin 8				
Output current		IO	3	mA	
Synchronization	Pin 4				
Input current		±I _{Sync.}	5	mA	
$t \le 10 \ \mu s$		i _{Sync.}	20	mA	
Window monitoring					
Input voltage	Pin 6	$-V_1$	V _{Ref} to 0	V	
Enable-Schmitt trigger	Pin 5				
Input voltage		-V ₁	V _{Ref} to 0	V	
Driver output	Pin 3			•	
Collector voltage		-V _o	V _S to 2	V	
Storage temperature range		T _{stg}	-40 to +125	°C	
Junction temperature	Ti	125	°C		
Ambient temperature range		T _{amb}	0 to 100	°C	

Thermal Resistance

Parameters		Symbol	Value	Unit
Junction ambient	DIP8	R _{thJA}	110	K/W
	SO8 on PC board	R _{thJA}	220	K/W
	SO8 on ceramic	R _{thJA}	140	K/W

Electrical Characteristics

 $V_S = -18$ V, $T_{amb} = 25^{\circ}C$, reference point Pin 1, unless otherwise specified

Parameters	Test Conditions / Pins	Symbol	Min	Тур	Max	Unit
Supply voltage limitation	$I_S = 800 \ \mu A$ Pin 2	-V _S	21		23	V
	$I_S = 2 mA$		21.3		24	V
Current consumption	$I_3 = 0$	-Is			750	μA
Supply voltage monitoring	g Pin 2					
ON-Threshold		-V _S		15		V
OFF-Threshold		-V _S		6.5		V
Reference voltage	$I_8 = 0.1 \text{ mA}$ Pin 8	-V _{Ref}	4.75		5.25	V
	$I_8 = 1.5 \text{ mA}$		4.55		5.25	V
Synchronization	Pin 4					
Input current		± i _{sync}	0.1		1.1	mA
Voltage limitation	$I_4 = \pm 1 \text{ mA}$	±V _{sync}	8.8	9.4	10	V
Rest phase angle	ON	±VT	3.6	4	4.4	V
α_{\min} -threshold	Off	$\pm V_T$	1.8	2	2.2	V
Zero-identification	Pin 4					
Zero-identification	ON	$\pm V_{T}$		1.5		V
		$\pm I_T$		8.5		μΑ
	OFF	±V _T		4		V
		±IT		20		μΑ
Operation selection	Pin 4	1				
Zero voltage switch		±V _{sync}		V ₄ limit		
α_{\min} -operation		+V _{sync}		V ₄ limit		V
		-V _{sync}		6.5 to 7.8		V
DC mode		-V _{sync}		V ₄ limit		V
		+V _{sync}		6.5 to 7.8		V
Window monitoring figure	Pin 6	1		1		1
Threshold 1		-V _I /V _{Ref}	0.52	0.49	0.46	
Threshold 2		-V _I /V _{Ref}	0.67	0.65	0.63	
Enable-Schmitt trigger	Pin 5					1
Threshold 1	OFF	-V _I /V _{Ref}	0.33	0.3	0.27	
Threshold 2	ON	-V _I /V _{Ref}	0.62	0.6	0.58	
Oscillator	$f = \frac{1}{1.6 \times R_t \times C_t}$					
Threshold 1	Pin 7 – 1	V _I /V _{Ref}	0.25	0.20	0.15	
Threshold 2	Pin 7 – 8	VI		100	200	mV
Input current	Pin 7	II		100	500	nA
Output stage limiter diod	e w.r.t. Pin 1 Pin 3					
Saturation voltage	$I_3 = 100 \text{ mA}$	V ₃₋₂			2	V
Output current		I ₃	100			mA

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Applications

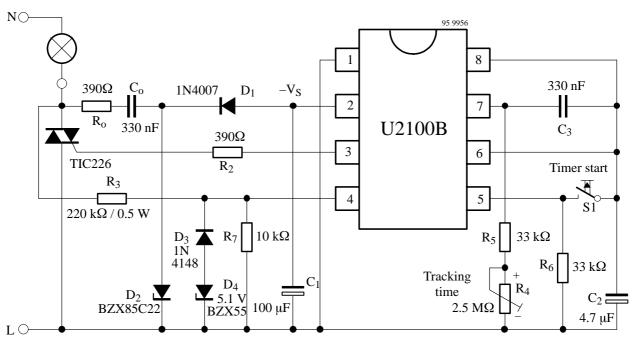


Figure 9. Lamp time control 18 sec. to 23 min. for two wire systems

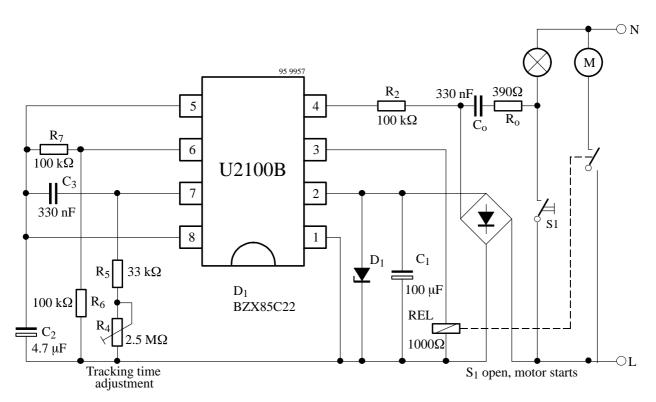


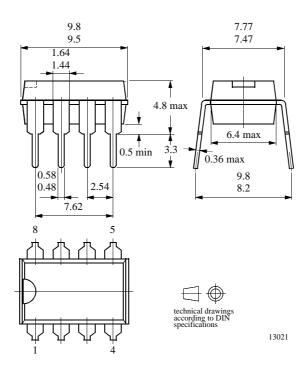
Figure 10. Fan tracking time control 18 sec. to 23 min.



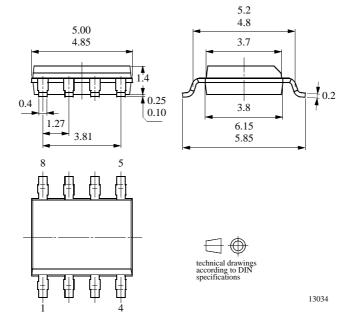
Package Information

Package DIP8

Dimensions in mm



Package SO8 Dimensions in mm



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- 1. Meet all present and future national and international statutory requirements.
- 2. Regularly and continuously improve the performance of our products, processes, distribution and operating systems with respect to their impact on the health and safety of our employees and the public, as well as their impact on the environment.

It is particular concern to control or eliminate releases of those substances into the atmosphere which are known as ozone depleting substances (ODSs).

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TEMIC Semiconductor GmbH semiconductor division has been able to use its policy of continuous improvements to eliminate the use of ODSs listed in the following documents.

- 1. Annex A, B and list of transitional substances of the Montreal Protocol and the London Amendments respectively
- 2. Class I and II ozone depleting substances in the Clean Air Act Amendments of 1990 by the Environmental Protection Agency (EPA) in the USA
- 3. Council Decision 88/540/EEC and 91/690/EEC Annex A, B and C (transitional substances) respectively.

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